INTRODUCTION TO QUANTUM MECHANICS PRINCIPLES

1ST LECTURE FROM THE COURSE QUANTUM PHYSICS OF LOW DIMENSIONAL STRUCTURES

QPLDS

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- 2. Postulates of quantum mechanics
- 3. Pure and mixed states
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FUNDAMENTAL QUANTUM QUANTITIES

1) A physical state (PS) of a quantum system,

2) A physical <u>quantity</u> (PQ) or an observable - to be eventually measured somehow.

POSTULATES OF QUANTUM MECHANICS

- 1) For the every PS there exists a vector of state, sometimes represented by the wave-function Ψ ,
- 2) For every PQ there exists a linear operator PQ (this works in the Hilbert space (HS) HS is a complete, unitary space equipped with the complex scalar product, which can be expressed by $\int \Psi^* \Psi dV$),
- 3) If a measurement of PQ gives a single result, then f(PQ), where f is a function of PQ, also gives a single results (sometimes complex PQ's are derived from direct measurements of some others PQ's and this approach is completely clear-cut),
- 4) Quantum aspect of classical quantities can be achieved by their replacement by appropriate operators followed by the replacement of the classical Poisson bracket by the commutation relation:

$$(A,B) = \sum_{k} \left(\frac{\partial A}{\partial x_{k}} \frac{\partial B}{\partial p_{k}} - \frac{\partial A}{\partial p_{k}} \frac{\partial B}{\partial x_{k}} \right) \rightarrow [A_{i}, B_{j}] = i\hbar \delta_{ij}$$

- 5) The averaged, and thus measurable, value of PQ can be calculated from the minimized value of the $\int \Psi^* PQ \Psi dV$ expression,
- 6) and from 5. results the existence of the equation of state (ES)

$$\stackrel{\widehat{PQ}}{\Psi} = C\Psi$$

and possible (averaged) $C = \langle PQ \rangle$ values of the measured PQ.

THE PROOF OF THE POSTULATE No 6

1)
$$\int \Psi^* \stackrel{\wedge}{PQ} \Psi dV = \lambda = const., \qquad \int \Psi^* \Psi dV = 1$$

- 2) we look for minimum of $\int \Psi^* PQ \Psi dV$, thus for the minimum-valued Ψ function,
- 3) $\int \Psi^* \stackrel{\frown}{PQ} \Psi dV = \lambda = 1 \cdot \lambda = \lambda \int \Psi^* \Psi dV \implies \int \Psi^* \stackrel{\frown}{PQ} \Psi dV \lambda \int \Psi^* \Psi dV = 0$
- 4) If Ψ is minimized, then there exists $\Psi' = \Psi + \delta \Psi$, $\delta \Psi' = \delta \Psi$ and $\int \Psi'^* PQ \Psi' dV \lambda \int \Psi'^* \Psi' dV \neq 0, \qquad \int \Psi'^* \Psi' dV \neq 1$, but $\delta \left[\int \Psi'^* PQ \Psi' dV \lambda \int \Psi'^* \Psi' dV \right] = 0$
- 5) $\int \partial \Psi'^* \stackrel{\frown}{PQ} \Psi' dV + \int \Psi'^* \delta(\stackrel{\frown}{PQ} \Psi') dV \lambda \int \partial \Psi'^* \Psi' dV \lambda \int \Psi'^* \partial \Psi' dV = 0$ - second integral: $\int \Psi'^* \delta(\stackrel{\frown}{PQ} \Psi') dV = \int \Psi'^* \stackrel{\frown}{PQ} \delta(\Psi') dV = \int (\stackrel{\frown}{PQ} \Psi')^* \partial \Psi' dV$ because: a) the variation doesn't influence operator
 - b) the $\stackrel{\frown}{PQ}$ is a hermitian operator $(\int u^* \stackrel{\frown}{PQ} w dV = \int (\stackrel{\frown}{PQ} u)^* w dV)$
- 6) $\int \partial \Psi'^* \stackrel{\frown}{PQ} \Psi' dV + \int (\stackrel{\frown}{PQ} \Psi')^* \partial \Psi' dV \lambda \int \partial \Psi'^* \Psi' dV \lambda \int \Psi'^* \partial \Psi' dV = 0$

7) next, 1st term is combined with the 3rd, and 2nd with the 4th:

$$\int \partial \Psi'^* (\stackrel{\wedge}{PQ} \Psi' - \lambda \Psi') dV + \int (\stackrel{\wedge}{PQ}^* \Psi'^* - \lambda \Psi'^*) \partial \Psi' dV = 0$$

and
$$(\stackrel{\smallfrown}{PQ}\Psi'-\lambda\Psi')=0$$
 and $\stackrel{\rightharpoonup}{(PQ}\Psi'^*-\lambda\Psi'^*)=0$, thus $\stackrel{\rightharpoonup}{PQ}\Psi'=\lambda\Psi'$, we are quite close to the final

8) the helpful extra derivation. Let's use $\Psi' = \Psi + \partial \Psi$, thus

$$\stackrel{\wedge}{PQ}(\Psi + \partial \Psi) = \lambda(\Psi + \partial \Psi)$$

$$\stackrel{\wedge}{PQ}(\Psi) + \stackrel{\wedge}{PQ}(\partial \Psi) = \lambda \Psi + \lambda(\partial \Psi)$$

$$\stackrel{\wedge}{PQ}(\Psi) - \lambda \Psi = \lambda(\partial \Psi) - \stackrel{\wedge}{PQ}(\partial \Psi)$$

9) Thus, <u>right hand side</u> of the above: $\lambda(\partial \Psi) - \hat{PQ}(\partial \Psi)$ should equals

$$\lambda(\partial \Psi) - \stackrel{\wedge}{PQ}(\partial \Psi) = \lambda(\partial \Psi) - \stackrel{\wedge}{\delta(PQ\Psi)} = \begin{vmatrix} \delta(\lambda \Psi) = \underbrace{(\delta \lambda)}_{=0} \Psi + \lambda \delta \Psi = \\ = \lambda \delta \Psi \end{vmatrix} = = \lambda \delta \Psi$$

$$= \delta(\lambda \Psi) - \delta(\stackrel{\wedge}{PQ} \Psi) = \delta(\lambda \Psi - \stackrel{\wedge}{PQ} \Psi) = -\delta(\stackrel{\wedge}{PQ} \Psi - \lambda \Psi)$$

However

$$L = -\delta L \iff L = 0$$

$$\stackrel{\wedge}{PQ}\Psi = \lambda\Psi \qquad \qquad \left(-\frac{\hbar^2}{2m}\frac{d^2}{dx^2} + V(x)\right)\Psi = E\Psi$$

$$\left(-\frac{\hbar^2}{2m}\frac{d^2}{dx^2} + V(x)\right)\Psi = E\Psi$$

PURE PS AND MIXED PS

PURE

 $| >= \lambda_1 | 1 > + \lambda_2 | 2 >$, all the elements in the formula are from the Hilbert space, in other words the vectors represent the PS (physical state vector); the components |1>, |2> and the superposition |>.

> Again; the mentioned state-vectors | > exist in reality, are REALLY POSSIBLE IN PHYSICAL REALITY

$$\psi = \lambda_1 \varphi_1 + \lambda_2 \varphi_2$$

$$\psi^* = \lambda_1 \varphi_1^* + \lambda_2 \varphi_2^*$$

$$< |= \lambda_1 < 1| + \lambda_2 < 2|$$

$$\sqrt{\int \psi^* \psi \, dV} = 1$$

$$|< | > |= 1$$

however $\psi e^{-i\alpha}$ determined with the restricted accuracy due to the $e^{-i\alpha}$ phase factor,

MIXED

In the mixed state <u>not EVERYTHING</u> is REALLY possible!?

WE GET PROBLEM
I MEAN
WE HAVE TO WAIT...

before <u>EVÉRYTHING</u> the STATISTICAL OPERATOR of the PURE STATE has to be defined

A STATISTICAL OPERATOR

Question: what we measure in quantum mechanics?

Let assume: we have the observable O and the state-vector |ps>, thus |s| = |ps| = |ps|

Next,

$$|ps> = \sum_{i} |i> < i|ps> = |1> < 1|ps> + |2> < 2|ps> = |1> \lambda_1 + |2> \lambda_2,$$

because

$$| ps >= \lambda_1 | 1 > + \lambda_2 | 2 >$$

$$<1 \mid ps> = \lambda_{1} < 1 \mid 1 > + \lambda_{2} < 1 \mid 2 > \Rightarrow <1 \mid ps> = \lambda_{1}, \text{ etc,}$$

$$< ps \mid = \sum_{k} < ps \mid k > < k \mid = < ps \mid 1 > <1 \mid + < ps \mid 2 > <2 \mid = \lambda_{1} <1 \mid + \lambda_{2} <2 \mid$$

$$< O>_{ps} = \sum_{k} \sum_{i} < ps \mid k > < k \mid O \mid i > =$$

$$= \sum_{k} \sum_{i} < k \mid O \mid i > < ps \mid k > =$$

$$= \sum_{k} \sum_{i} < k \mid O \mid i > < ps \mid k > =$$

$$= \sum_{k} \sum_{i} < k \mid O \mid i > < ps \mid k >$$

Let's check again the double-sum term:

$$[\langle ps | 1 \rangle \langle 1 | + \langle ps | 2 \rangle \langle 2 |]O[|1 \rangle \langle 1 | ps \rangle + |2 \rangle \langle 2 | ps \rangle] =$$

$$\langle ps | 1 \rangle \langle 1 | O | 1 \rangle \langle 1 | ps \rangle + \langle ps | 1 \rangle \langle 1 | O | 2 \rangle \langle 2 | ps \rangle +$$

$$+ \langle ps | 2 \rangle \langle 2 | O | 1 \rangle \langle 1 | ps \rangle + \langle ps | 2 \rangle \langle 2 | O | 2 \rangle \langle 2 | ps \rangle =$$

$$= \langle 1 | O | 1 \rangle \langle 1 | ps \rangle \langle ps | 1 \rangle + \langle 1 | O | 2 \rangle \langle 2 | ps \rangle \langle ps | 1 \rangle +$$

$$+ \langle 2 | O | 1 \rangle \langle 1 | ps \rangle \langle ps | 2 \rangle + \langle 2 | O | 2 \rangle \langle 2 | ps \rangle \langle ps | 2 \rangle =$$

$$= <1 | O | ps > < ps | 1 > + < 2 | O | ps > < ps | 2 > =$$

$$= \sum_{k} < k | O | SO_{ps} | k > = Tr(OSO_{ps}) = < O >_{ps},$$

where $SO_{ps} = |ps\rangle\langle ps|$

is the STATISTICAL OPERATOR OF THE PURE STATE BUILT FROM THE STATE VECTOR $\mid ps>$,

Remarks:

- a) $SO_{ps} = |ps> < ps|$ is used in calculation of the average value of the observable $< O>_{ps}$,
- b) the $< O>_{ps}$ is calculated completely precisely, with no $e^{-i\alpha}$ phase factor like in the method using wave-function formalism $< O>_{ps} = < ps \mid O \mid ps >$.

COME BACK

TO

MIXED STATES...

MIXED

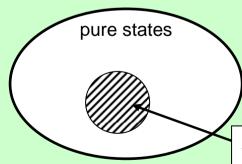
A mixed state is composed from pure states and this can be expressed using statistical operators language as follows

$$SO_{mx} = \sum_{k} p_k SO_{sp(k)}$$

$$SO_{mx} = \sum_{k} p_{k} \mid ps_{k} > \langle ps_{k} \mid$$
$$\langle O \rangle_{mx} = \sum_{k} p_{k} \langle O \rangle_{sp(k)}$$

$$< O >_{mx} = \sum_{k}^{\infty} p_k Tr(O SO_{sp(k)}) = Tr(O \sum_{k} p_k SO_{sp(k)}) = Tr(O SO_{mx})$$

$$< O >_{mx} = Tr(OSO_{mx})$$



the mixed state: created after tunneling of the two spins through a barrier and determined by the projection onto the welldefined direction (local magnetic field), but the mixture on the pure states is determined by their probabilities

A part of the pure-states set is a mixed state

A PICTURE OF THE TIME EVOLUTION – the first probe (THE EVOLUTION TO BETTER KNOWLEDGE DUE TO THE KNOWLEDGE EVOLUTION J)

The evolution operator $G(t,t_0)$

$$|t>\stackrel{def}{=}G(t,t_0)|t_0> \text{ and } G^+(t,t_0)|t>=|t_0>$$

↑These are very general formulas↑

The aim is to show how are dependent on time:

- a) a vector of a physical state (PS),
- b) a statistical operator (SO),
- c) an observable (O).

SCHRÖDINGER

The existence of the equation of state (ES) was proved as the extension of the postulate 6.

In the SCHRÖDINGER picture the ES has the following form

$$\left| -\frac{\hbar}{i} \frac{\partial}{\partial t} \right| t >= H \mid t >$$

THE STARTING POINT IS THE TIME EVOLUTION OF THE STATE VECTOR $\mid t >$

- after substitution of $|t\rangle = G(t,t_0) |t_0\rangle$ into the ES:

$$-\frac{\hbar}{i}\frac{\partial}{\partial t}G(t,t_0) = HG(t,t_0), \ G(t_0,t_0) = I$$

- from that results the solution for $G(t,t_0)$:

$$G(t,t_0) = e^{-iH(t-t_0)/\hbar}$$

$$G^{+}(t,t_{0}) = e^{iH(t-t_{0})/\hbar} = G^{-1}(t,t_{0})$$
$$G(t,t_{0})G^{-1}(t,t_{0}) = I$$

- the SO operator time-behavior:

for the pure state:

$$SO_{sp}(t) = |t| < t |= G(t, t_0) |t_0| < t_0 |G^+(t, t_0)| = G(t, t_0) SO_{sp}(t_0) G^+(t, t_0)$$

$$SO_{sp}(t) = G(t, t_0)SO_{sp}(t_0)G^+(t, t_0)$$

for the mixed state:

$$SO_{mx}(t) = \sum_{k} p_{k} | t, k > < t, k | = \sum_{k} p_{k}G(t, t_{0}) | t_{0}, k > < t_{0}, k | G^{+}(t, t_{0}) =$$

$$= G(t, t_{0}) \sum_{k} p_{k} | t_{0}, k > < t_{0}, k | G^{+}(t, t_{0}) = G(t, t_{0}) \sum_{k} p_{k}SO_{sp}(t_{0})G^{+}(t, t_{0})$$

$$SO_{mx}(t) = G(t, t_0)SO_{mx}(t_0)G^+(t, t_0)$$

Thus, after differentation of the above for $SO_{mx}(t)$

$$-\frac{\hbar}{i}\frac{\partial SO_{mx}(t)}{\partial t} = -\frac{\hbar}{i}\frac{\partial G}{\partial t}SO_{mx}(t_0)G^+ - \frac{\hbar}{i}GSO_{mx}(t_0)\frac{\partial G^+}{\partial t} = HGSO_{mx}(t_0)G^+ - GSO_{mx}(t_0)G^+H$$

then

$$-\frac{\hbar}{i}\frac{\partial SO_{mx}(t)}{\partial t} = [H, SO_{mx}(t)], \text{ and } \frac{\partial H}{\partial t} \equiv 0$$

SCHRÖDINGER summarizes:

the PS evolves in time

$$|t> = G(t,t_0) |t_0>$$

the SO evolves in time

$$-\frac{\hbar}{i}\frac{\partial SO_{mx}(t)}{\partial t} = [H, SO_{mx}(t)]$$

and the O does not evolves in time $\frac{\partial O}{\partial t} \equiv 0$

A PICTURE OF THE TIME EVOLUTION – the second probe THE STATISTICAL OPERATOR EVOLUTION – some derivations

$$1) < O >_{mx} = Tr(OSO_{mx})$$

2)
$$SO_{mx}(t) = G(t,t_0)SO_{mx}(t_0)G^+(t,t_0)$$

3) $(2) \rightarrow (1)$:

$$< O >_{mx} = Tr[OSO_{mx}(t)] = Tr[OG(t,t_0)SO_{mx}(t_0)G^+(t,t_0)]$$

HEISENBERG

<u>Something new</u>; a transformation of the observable O into the Heisenberg picture O_H :

$$O_H \stackrel{def}{=} G^+(t, t_0) O G(t, t_0)$$

From this results, for any arbitrary observable O, that $O = O_H(t_0)$, especially $H = H_H(t_0)$ as $G^+(t_0, t_0) = G(t_0, t_0) = 1$.

and again, something new; a transformation of the state vector |t> into the Heisenberg picture $|t>_H$

$$|t>_{H}^{def}=G^{+}|t>$$

There is a <u>subtle difference</u> between the Heisenberg-like behavior for the statistical operator (SO) and the state-vector $|t\rangle$ "at the beginning", for t_0 , namely

$$|t>_{H} = |t_0>$$
 and $O_H(t_0)=O$

what reads: only at the beginning the Schrödinger state vector equals the Heisenberg state-vector, <u>and</u>, only at the beginning the Heisenberg observable equals the observable from the Schrödinger point of view.

HOWEVER, from the above results that, in the Heisenberg picture:

- a) a state vector doesn't evolve in time,
- b) a statistical operator doesn't evolve in time,
- c) an observable evolves in time.

Ad. a -
$$|t>_H = |t_0>$$
?!
$$|t>_H = G^+G \, |\, t_0> = |t_0> \, , \, \text{here you are}.$$

Ad. b -
$$SO_H(t)$$
 ?!
$$SO_H(t) = G^+SO_{mx}(t)G = G^+GSO_{mx}(t_0)G^+G = SO_{mx}(t_0) \text{ , that's it.}$$

Ad. c -
$$O_H(t)$$
 ?!

well...

As we know
$$O_H \stackrel{def}{=} G^+(t,t_0) \, O \, G(t,t_0) = G^+ O \, G$$
 ,

then, after differentation of the above and taking advantage from $G=e^{-iH(t-t_0)/\hbar}$

we have

$$-\frac{\hbar}{i}\frac{\partial O_H(t)}{\partial t} = -\frac{\hbar}{i}\frac{\partial G^+}{\partial t}OG^+ - \frac{\hbar}{i}G^+O\frac{\partial G}{\partial t} = G^+OGH - HG^+OG = O_HH - HO_H$$
 thus

$$\boxed{-\frac{\hbar}{i}\frac{\partial O_H(t)}{\partial t} = \left[O_H(t), H\right]}$$

now HEISENBERG summarizes:

the PS_H doesn't evolve in time

$$\frac{\partial |t>_{H}}{\partial t} \equiv 0$$

the SO_H doesn't evolve in time

$$\boxed{\frac{\partial \mid SO>_{H}}{\partial t} \equiv 0}$$

and the O_H evolves in time

$$\frac{1}{i} \frac{\partial O_H(t)}{\partial t} = \left[O_H(t), H \right]$$

A PICTURE OF THE TIME EVOLUTION – the third probe

TOMONAGA

THE STARTING POINT IS THE SPLIT OF THE HAMILTONIAN INTO THE 2 PIECES;

- a) that of the free particles or free physical fields,
- b) that of the interaction between the above.

$$H = H^{(0)} + H^{(1)}$$

The free evolution operator

$$G_0 = e^{-iH^{(0)}(t-t_0)/\hbar}$$

The evolution of the state vector

$$|t>_T = G_0^+ |t>$$

while $|t_0>_T=|t_0>$.

Thus

$$\frac{\partial |t>_{T}}{\partial t} = -\frac{\hbar}{i} G_{0}^{+} H^{(1)} G |t>_{T},$$

or

$$-\frac{\hbar}{i} \frac{\partial |t>_{T}}{\partial t} = H_{1} |t>_{T}$$

where
$$H_1 = G_0^+ H^{(1)} G_0$$

The modified evolution operator of Tomonaga G_T

$$|t>_T = G_0^+ |t> = G_0^+ G |t_0> = G_0^+ G |t_0>_T = G_T |t_0>_T = G_$$

$$G_T = G_0^+ G = e^{-iH^{(1)}(t-t_0)/\hbar}$$

After substitution of $|t>_T = G_T |t_0>_H$ into the Tomonaga evolution

equation
$$-\frac{\hbar}{i} \frac{\partial |t>_T}{\partial t} = H_1 |t>_T \text{ we have}$$

$$-\frac{\hbar}{i}\frac{\partial SO_{T}(t)}{\partial t} = -\frac{\hbar}{i}\frac{\partial G_{0}^{+}}{\partial t}SOG_{0} - \frac{\hbar}{i}G_{0}^{+}\frac{\partial SO}{\partial t}G_{0} - \frac{\hbar}{i}G_{0}^{+}SO\frac{\partial G_{0}}{\partial t}$$

and finally,

$$-\frac{\hbar}{i}\frac{\partial SO_{T}(t)}{\partial t} = \left[H_{1}(t), SO_{T}(t)\right]$$

and

$$-\frac{\hbar}{i}\frac{\partial O_T(t)}{\partial t} = \left[O_T(t_0), H^{(0)}\right]$$

now TOMONAGA summarizes:

the PS_T evolves in time

$$-\frac{\hbar}{i} \frac{\partial |t>_{T}}{\partial t} = H_{1} |t>_{T}$$

the SO_T evolves in time

$$-\frac{\hbar}{i}\frac{\partial SO_{T}(t)}{\partial t} = \left[H_{1}(t), SO_{T}(t)\right]$$

and the O_T evolves in time

$$\left[-\frac{\hbar}{i} \frac{\partial O_T(t)}{\partial t} = \left[O_T(t_0), H^{(0)} \right] \right]$$

EVERYBODY SUMMARIZE ABOUT THE EVOLUTION

Picture	PS	SO	0
Schrödinger	yes	yes	no
Heisenberg	no	no	yes
Tomonaga	yes	yes	yes

HOWEVER

$$< O>_{mx} = < O>_{H} = < O>_{T}$$

What is accessible in experimental reality is the same